

# **SFPG Series Air Gripper**

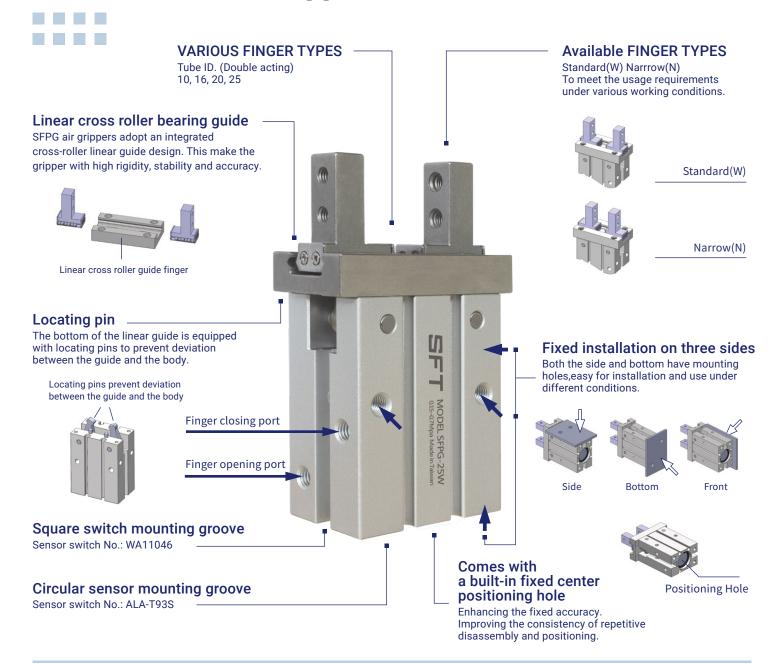






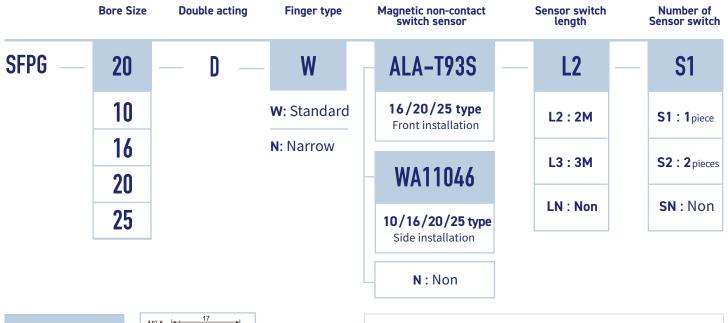


# **SFPG Series Air Gripper**

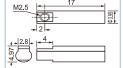


Tube ID (mm)	Style	Operation	Operating pressure range  Double Acting	Operating Temperature	Lubricator	Repeatability (mm)	Max. operating frequency	Installation	Port size	Sensor switch
10			<b>0.2~0.7 MPa</b> (28~100 psi) (2.0~7.0 bar)	-20~70°C	No need	±0.01		1. Side	M3 X 0.5	<b>WA11046</b> (Side)
16	Double						<b>180</b> (c.p.m)	2. Front tapped hole 3. Front through hole		
20	acting		<b>0.15~0.7 MPa</b> (22~100 psi) (1.5~7.0 bar)					4. Bottom	M5 X 0.8	ALA-T93S (Front) WA11046 (Side)
25										(5.26)



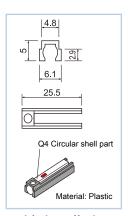


ALA-T93S



Front installation

WA11046



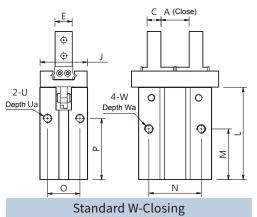
Side installation

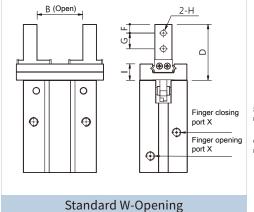
When securing to indicated in below	the sensor switch the sensor switch, please insert it in the direction ow illustration, place it in position, and then tighten the nsor with a a flat blade watchmaker's screwdriver.
Flat blade watch	nmaker's screw driver
Sensor switch se M2.5x4L  Sensor switch	et screw

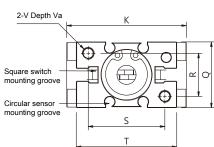
Air Gripper Comparison Table										
SFT	SMC	Mindman	AirTAC							
SFPG-16D (Cross Roller)	MHZ2-16D(Ball)	MCHC-16D(Ball)	HFZ-16D(Ball) HFK-16D(Roller)							
SFPG-20D (Cross Roller)	MHZ2-20D(Ball)	MCHC-20D(Ball)	HFZ-20D(Ball) HFK-20D(Roller)							

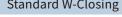
# **Features**

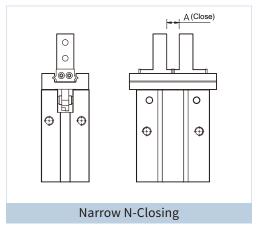
- 1 The gripper utilizes crossed roller guide rails, providing better rigidity and higher precision.
- 2 Gripper lifespan test for 5 million opening and closing cycles.
- 3 German Klüber lubrication.
- 4 Crossed Rollers made in Japan.

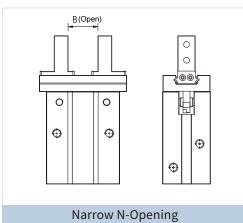


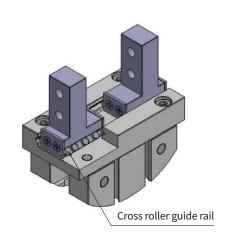












Bore Size	Α	В	С	D	Е	F	G	Н	1	J	К	L	М	N	0	Р
SFPG10W	10.5 +0	16.5 +2	4	19	5	3	5.7	M2.5	6	16	29	37.8	23	16	11.5	27
SFPG10N	6 <sup>+0</sup>	10 +2	4	19	5	3	5.7	M2.5	6	16	29	37.8	23	16	11.5	27
SFPG16W	16 +0	21 +2	5	24.8	8	4	7	М3	7.5	23	38	42.5	24.5	24	16	30
SFPG16N	6.5 +0	12 +2	5	24.8	8	4	7	М3	7.5	23	38	42.5	24.5	24	16	30
SFPG20W	16.5 +0	26.5 +2	8	32	10	5	9	M4	9.4	27	50	52.8	29	30	18.5	35
SFPG20N	7 <sup>+0</sup>	17 +2	8	32	10	5	9	M4	9.4	27	50	52.8	29	30	18.5	35
SFPG25W	19.5 +0	33.5 +2	10	39	12	6	12	M5	11	33	71	64	30	36	22	36.5
SFPG25N	9 +0	23 +2	10	39	12	6	12	M5	11	33	71	64	30	36	22	36.5

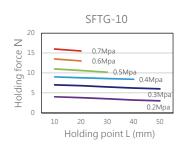
Bore Size	Q	R	S	Т	U	Ua	٧	Va	W	Wa	Χ	Weight/g	Acting type	External clamping Force(N)	Internal clamping Force(N)	Lubricatior
SFPG10W	16.5	12	19	23	M3	6	M3	6	M3	6	M3	56	Double acting	16	10	Few/ Not need
SFPG10N	16.5	12	19	23	M3	6	M3	6	М3	6	M3	56	Double acting	16	10	Few/ Not need
SFPG16W	23.5	15	22	30.5	M4	6	M4	8	M4	8	M5	113	Double acting	44	33	Few/ Not need
SFPG16N	23.5	15	22	30.5	M4	6	M4	8	M4	8	M5	113	Double acting	44	33	Few/ Not need
SFPG20W	27.5	18	32	42	M5	9	M5	11	M5	11	M5	228	Double acting	65	42	Few/ Not need
SFPG20N	27.5	18	32	42	M5	9	M5	11	M5	11	M5	228	Double acting	65	42	Few/ Not need
SFPG25W	33.5	22	40	52	M6	10	M6	12	M6	12	M5	420	Double acting	102	63	Few/ Not need
SFPG25N	33.5	22	40	52	M6	10	M6	12	M6	12	M5	420	Double acting	102	63	Few/ Not need

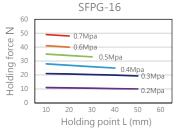
Bore Size	Round sensor switch	Square sensor switch	Body	Rod cover	Gasket	Guide	Gripper	Actuating lever	Rolling element	Repeatability	Working place temperature	Operating frequency	Operating presssure range	Max. operating presssure range
SFPG10W	NON													
SFPG10N	NON													
SFPG16W														
SFPG16N			Aluminum	Stainless	NBR	SUS	SUS	SUS	Roller SUJ2	0.01mm	0°C ~50°C	150/S	1~7kgf/cm² 0.1~0.7MPa	
SFPG20W	Ø4	6.3*4mm	n alloy	Steel										
SFPG20N	<i>1</i> 04													
SFPG25W														
SFPG25N														

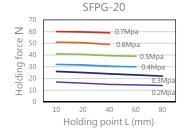


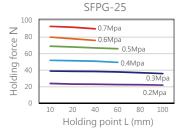
#### Select the model based Check the conditions Calculate the required gripping clamping force on the clamping force diagram Workpiece mass: 0.1kg Reference for machine selection based on the workpiece mass SFPG-16D Varies according to accessories, the workpiece friction External diameter clamping force coefficient and shape. Clamping method: SFPG-16 Please select obtained capacity that is 10 to 20 times the External diameter clamping weight of the workpiece. Z 50 0.7Mpa Additionally, during the transportation of the workpiece force 40 when there is a high acceleration and impact force . Much 0.5Mpa 30 more sufficient safety factor is necessary. 0.4Mpa 0.3Mpa Holding 20 EX: Clamping force need to be more than 20 times the 10 weight of the workpiece. greater than the workpiece weight: Requested clamping force= 0.1 kg x 20 x 9.8 m/s2 $\approx$ 19.6 N Holding point L (mm) According to clamping distance L=at 30 mm and 0.4 MPa, the clamping force is determined to Clamping point: 30mm be 24 N. The clamping force is 24.5 times the mass of the workpiece, exceeding the satisfies a gripping force setting Operating pressure: 0.4 Mpa value of 20 times or more.

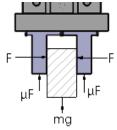
## **Holding Force**











### Clamping the workpiece as shown in the diagram

F: Clamping force [N]

 $\mu$ : Coefficient of friction between the gripper and Workpiece

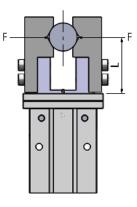
m: Workpiece mass (kg)

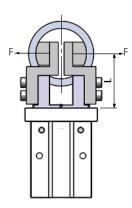
g: Acceleration (=9.8m)/s<sup>2</sup>

mg: Workpiece weight (N)

The conditions under which the workpiece will not drop are:

$$2 \times \mu F > mg \ (2 : \text{Number of fingers})$$
 Therefore 
$$F > \frac{mg}{2 \times \mu}$$
 
$$F = \frac{mg}{2 \times \mu} \times a \ (\text{Safety factor})$$





μ=0.2	μ=0.1
$F = \frac{mg}{2 \times 0.2} \times 4$ $= 10 \times mg$	$F = \frac{mg}{2 \times 0.1} \times 4$ $= 20 \times mg$
10 x Workpiece weight	20 x Workpiece weight

<sup>\* 1.</sup>For safety, please choose a machine with a workload 10 to 20 times the weight of the workpiece when the coefficient of friction (u) is greater than 0.2

when the coefficient of friction ( $\mu$ ) is greater than 0.2. \* 2. In cases of higher acceleration or usage with impact conditions, it's also necessary to allocate a larger safety factor.



#### Solid state electronic auto switch

#### Features:

- 1 The two-wire parallel connection can replace the original sensor switch with the same wiring method.
- 2 No-contact solid-state electronic sensors utilize chip-based sensing without the need for electrical connections and are compatible with the entire 3 range of pneumatic grippers, eliminating the need for contact points.
- 3 Sensor switch with long lifespan, impact-resistant, and withstand vibrations. This is in contrast to glasses type, which are more prone to breakage.
- 4 The sensing magnetic field range covers the entire spectrum from 25 to 500 gauss, ensuring single-touch and error-free operation with high sensitivity and high repeatability. There are no issues with secondary induction or missed detections.
- 5 It can replace 3-wire NPN and PNP sensors.

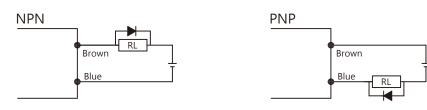
Model	ALA-T93S	ALA-T93L (For light current)				
Cable type	2-v	vire				
Switch	Normal	ly Close				
Connection type	Electrical au	ıto switches				
Loading capacity	24VDC Reload,PLC	IC circuit				
Voltage range	24VDC ( 6-30V DC )	24VDC ( 20-30V DC )				
Current range	100m/	A max.				
Connection capacity	0.6W	max.				
Power consumption	0.02 m					
Voltage drop	4V max.					
Leakage current	0.65mA max.	0.135mA max.				
Impact resistance	50G					
Vibration resistance	9G					
Allowable temperature range	-10°C~+70°C					
Cable type	2.9ø, 2C, PVC					
Cable length	2m, 3m, 5m					
Light on	Auto switch to tu	rn ON (Light ON)				
Insulation grade	IEC 529 IP67					
Light color	Red light					
Weight	12.8g (2m Cable ) / 23.8g (3m Cable )					
Circuit protection	Surge protection Device					



Solid state electronic auto switch



Fragile glasses tube switch



#### 3-Wire combine into 2-Wire



